# CDCL-based Abstract State Transition System for Coherent Logic

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# Overview

- Coherent logic (CL) and our motivation
- The CDCL-based abstract transition system for CL
- Related work
- Conclusions and further work

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What is Coherent Logic On the Other Hand: CDCL Solvers

# What is Coherent Logic

• Coherent logic is a fragment of FOL with formulae of form:

 $A_1(\vec{x}) \land \ldots \land A_n(\vec{x}) \Rightarrow \exists \vec{y}_1 \ B_1(\vec{x}, \vec{y}_1) \lor \ldots \lor \exists \vec{y}_m \ B_m(\vec{x}, \vec{y}_m)$ 

 $A_i$  are atoms,  $B_i$  are conjunctions of atoms

- No function symbols of arity greater than 0
- No negation
- Translation from FOL to CL
- The problem of deciding  $\Gamma \vdash \Phi$  is semi-decidable
- Intuitionistic logic
- First used by Skolem, recently popularized by Bezem et al.

What is Coherent Logic On the Other Hand: CDCL Solvers

# Why is CL interesting?

- A number of theories and theorems can be formulated directly and simply in CL
- Example: large fraction of Euclidean geometry belongs to CL
- Example: for any two points there is a point between them
- Conjectures in abstract algebra, confluence theory, lattice theory, and many more (Bezem et al)

Coherent Logic and Our Motivation

The CDCL-based Abstract Transition System for CL Related work Conclusions and further work What is Coherent Logic On the Other Hand: CDCL Solvers

# Good features of CL

- It is expressive
- It allows direct, readable and machine verifiable proofs
  - a simple, natural proof system (natural deduction style), based on forward ground reasoning
  - a conjecture is kept unchanged and proved directly (refutation, Skolemization and clausal form are not used)
  - existential quantifiers are eliminated by introducing witnesses

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**Coherent Logic and Our Motivation** 

The CDCL-based Abstract Transition System for CL Related work Conclusions and further work

# CL provers

What is Coherent Logic On the Other Hand: CDCL Solvers

- Euclid by Stevan Kordić and Predrag Janičić (1992)
- CL prover by Marc Bezem and Coquand (2005)
- ML prover by Berghofer and Bezem (2006)
- Geo by Hans de Nivelle (2008)
- ArgoCLP by Sana Stojanović, Vesna Pavlović and Predrag Janičić (2009)
- However, they are still not generally efficient

Coherent Logic and Our Motivation The CDCL-based Abstract Transition System for CL Related work

What is Coherent Logic On the Other Hand: CDCL Solvers

# Example: Proof Generated by ArgoCLP

Let us prove that p = r by reductio ad absurdum.

- 1. Assume that  $p \neq r$ .
  - It holds that the point A is incident to the line q or the point A is not incident to the line q (by axiom of excluded middle).
    - 3. Assume that the point A is incident to the line q.
      - From the facts that p ≠ q, and the point A is incident to the line p, and the point A is incident to the line q, it holds that the lines p and q intersect (by axiom ax\_D5).
      - 5. From the facts that the lines p and q intersect, and the lines p and q do not intersect we get a contradiction.

Contradiction.

- 6. Assume that the point A is not incident to the line q.
  - From the facts that the lines p and q do not intersect, it holds that the lines q and p do not intersect (by axiom ax.nint\_l\_l\_21).
  - 8. From the facts that the point A is not incident to the line q, and the point A is incident to the plane α, and the line q is incident to the plane α, and the point A is incident to the line p is incident to the plane α, and the line q is incident to the plane α, and the line q and p do not intersect, and the point A is incident to the line r, and the line r is incident to the plane α, and the lines q and r do not intersect, and the point A is incident to the line r is incident to the plane α, and the line q and r do not intersect, it holds that p = r (by axiom ax.E2).
  - 9. From the facts that p = r, and  $p \neq r$  we get a contradiction.

Contradiction.

Therefore, it holds that p = r.

This proves the conjecture.

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What is Coherent Logic On the Other Hand: CDCL Solvers

# On the Other Hand: CDCL Solvers

- SAT problem and SAT solvers
- SAT and SMT solvers are at rather mature stage
- The most efficient ones are CDCL solvers
- However, support for quantifiers depends on theory solvers (most theory solvers allow only quantifier free formulae)
- Producing readable and/or formal proofs is often challenging
- Goal: combine good features of CL and CDCL and build an efficient CDCL prover for CL

Abstract State Transition Systems for SAT Abstract State Transition Systems for CL

Abstract State Transition Systems for SAT

- Inspiration and starting point: transition systems for SAT
- First system: Nieuwenhuis, Oliveras, and Tinelli (2006)
- We build upon: the system by Krstić and Goel (2007)

Coherent Logic and Our Motivation The CDCL-based Abstract Transition System for CL Related work

Conclusions and further work

Abstract State Transition Systems for SAT

Abstract State Transition Systems for CL

# Krstić and Goel's System

Decide:
$I \in L$ $I, \overline{I} \notin M$
M := M   I
UnitPropag:
$I \lor I_1 \lor \ldots \lor I_k \in F$ $\overline{I}_1, \ldots, \overline{I}_k \in M$ $I, \overline{I} \notin M$
$M := M I^i$
Conflict:
$C = no\_cflct \qquad \overline{l}_1 \lor \ldots \lor \overline{l}_k \in F \qquad l_1, \ldots, l_k \in M$
$C := \{l_1, \ldots, l_k\}$
Explain:
$I \in C$ $I \lor \overline{l}_1 \lor \ldots \lor \overline{l}_k \in F$ $l_1, \ldots, l_k \prec I$
$C := C \cup \{l_1, \ldots, l_k\} \setminus \{l\}$
Learn:
$C = \{l_1, \ldots, l_k\} \qquad \overline{l_1} \lor \ldots \lor \overline{l_k} \notin F$
$F := F \cup \{\overline{l_1} \vee \ldots \vee \overline{l_k}\}$
Backjump:
$C = \{I, I_1, \dots, I_k\} \qquad \overline{I} \lor \overline{I}_1 \lor \dots \lor \overline{I}_k \in F \qquad \text{level } I > m \ge \text{level } I_i$
$C := no\_cflct$ $M := M^m \bar{l}^i$
Forget:
$C = no\_cflct$ $c \in F$ $F \setminus c \models c$
$F := F \setminus c$
Restart:
$C = no_{cflct}$
$M := M^{[0]}$

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# Setup

- Signature:  $\Sigma$ ; axioms:  $\mathcal{AX}$ ; conjecture:  $\forall \vec{x}(\mathcal{H}^0(\vec{x}) \Rightarrow \mathcal{G}^0(\vec{x}))$
- $\mathcal{H} = \mathcal{H}^0(\vec{x})\lambda$ ,  $\mathcal{G} = \mathcal{G}^0(\vec{x})\lambda$
- State:  $S(\Sigma, \Gamma, M, \mathcal{C}_1, \mathcal{C}_2, \ell)$
- Initial state:  $S_0(\Sigma_0, \mathcal{AX}, \mathcal{H}, \emptyset, \emptyset, |\Sigma_0|)$
- Accepting final state: a lemma is derived which implies the conjecture
- Rejecting final state: no rules are applicable
- Slightly extended CL language:

 $\forall \vec{x} \ p_1(\vec{v}, \vec{x}) \land \ldots \land \forall \vec{x} \ p_n(\vec{v}, \vec{x}) \Rightarrow \exists \vec{y} \ q_1(\vec{v}, \vec{y}) \lor \ldots \lor \exists \vec{y} \ q_m(\vec{v}, \vec{y})$ 

 $\mathcal{C}_1 := \mathcal{P}$ 

 $\mathcal{C}_2 := \mathcal{Q}$ 

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# CL state transition system (forward rules)

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# CL state transition system (backward rules)

Explain left  $\forall$ :

$$\begin{array}{ccc} \mathcal{C}_{1} \Rightarrow \mathcal{C}_{2} \downarrow^{m} & l \in m(\mathcal{C}_{1}) & \mathcal{S} = m^{-1}(l) & \mathcal{S} \Rightarrow \forall \vec{x} p(\vec{v}, \vec{x}) \\ \mathcal{P} \Rightarrow \mathcal{Q} \cup \{ p(\vec{v}', \vec{x}') \} \in \Gamma & \mathcal{P} \Rightarrow \mathcal{Q} \downarrow^{m'} & m'(\mathcal{P} \cup \mathcal{Q}) \prec l & \forall \vec{x} p(\vec{v}, \vec{x}) \times_{\lambda} p(\vec{v}', \vec{x}') \\ \mathcal{C}_{1} := (\forall \vec{x}' \mathcal{P} \cup (\mathcal{C}_{1} \setminus \mathcal{S})) \lambda & \mathcal{C}_{2} := (\exists \vec{x}' \mathcal{Q} \cup \mathcal{C}_{2}) \lambda \end{array}$$

Explain left ∃:

$$\begin{array}{ccc} C_1 \Rightarrow C_2 \downarrow^m & l \in m(\mathcal{C}_1) & \mathcal{S} = m^{-1}(l) & \mathcal{S} \Rightarrow_{\sigma} p(\vec{v}, \vec{x}) \\ \mathcal{P} \Rightarrow \mathcal{Q} \cup \{ \exists \vec{x}' p(\vec{v}', \vec{x}') \} \in \Gamma & \mathcal{P} \Rightarrow \mathcal{Q} \downarrow^{m'} & m'(\mathcal{P} \cup \mathcal{Q}) \prec l & \overline{p(\vec{v}, \vec{x})} \times_{\lambda} \exists \vec{x}' p(\vec{v}', \vec{x}') \\ C_1 := (\mathcal{P} \cup \forall \vec{x}(\mathcal{C}_1 \sigma \setminus \mathcal{S} \sigma))\lambda & C_2 := (\mathcal{Q} \cup \exists \vec{x}(\mathcal{C}_2 \sigma))\lambda \end{array}$$

Explain right ∀:

$$\begin{array}{ccc} C_1 \Rightarrow C_2 \downarrow^m & l \in m(C_2) & \mathcal{S} = m^{-1}(l) & \mathcal{S} \Rightarrow_{\sigma} p(\vec{v}, \vec{x}) \\ \frac{\{\forall \vec{x}' p(\vec{v}', \vec{x}')\} \cup \mathcal{P} \Rightarrow \mathcal{Q} \in \Gamma & \mathcal{P} \Rightarrow \mathcal{Q} \downarrow^{m'} & m'(\mathcal{P} \cup \mathcal{Q}) \prec l & p(\vec{v}, \vec{x}) \times_{\lambda} \forall \vec{x}' p(\vec{v}', \vec{x}') \\ \hline C_1 := (\mathcal{P} \cup \forall \vec{x}(\mathcal{C}_1 \sigma))\lambda & C_2 := (\mathcal{Q} \cup \exists \vec{x}(\mathcal{C}_2 \sigma \setminus \mathcal{S} \sigma))\lambda \end{array}$$

Explain right  $\exists$ :

$$\begin{array}{ccc} C_1 \Rightarrow C_2 \downarrow^m & l \in m(C_2) & \mathcal{S} = m^{-1}(l) & \mathcal{S} \Rightarrow \exists \vec{x} p(\vec{v}, \vec{x}) \\ \hline \{p(\vec{v}', \vec{x}')\} \cup \mathcal{P} \Rightarrow \mathcal{Q} \in \Gamma & \mathcal{P} \Rightarrow \mathcal{Q} \downarrow^{m'} & m'(\mathcal{P} \cup \mathcal{Q}) \prec l & \exists \vec{x} p(\vec{v}, \vec{x}) \times_{\lambda} \overline{p(\vec{v}', \vec{x}')} \\ \hline C_1 := (\forall \vec{x}' \mathcal{P} \cup C_1) \lambda & C_2 := (\exists \vec{x}' \mathcal{Q} \cup (C_2 \setminus \mathcal{S})) \lambda \end{array}$$

Learn:

$$\frac{\mathcal{C}_2 \neq \{\textit{no\_cflct}\} \quad \mathcal{C}_1 \Rightarrow \mathcal{C}_2 \notin \Gamma}{\Gamma := \Gamma^{\frown} \mathcal{C}_1 \Rightarrow \mathcal{C}_2}$$

Backjump:

$$\begin{array}{cccc} \mathcal{C}_1 \Rightarrow \mathcal{C}_2 \in \Gamma & \mathcal{C}_1 \Rightarrow \mathcal{C}_2 \downarrow^m & l \in m(\mathcal{C}_1) & \mathcal{S} = m^{-1}(l) & \mathcal{C}_1 \setminus \mathcal{S} \Rightarrow \mathcal{C}_2 \downarrow_{\lambda}^{m'} \\ \hline m' \subseteq m & m'(\mathcal{C}_1 \setminus \mathcal{S} \cup \mathcal{C}_2) \subseteq^n & M & l \in n' & M & n \leq t < n' & \mathcal{S}\lambda \Rightarrow l' \\ \hline M := M^{t < n} \overline{l'} & \Sigma := \Sigma^t & \mathcal{C}_1 := \emptyset & \mathcal{C}_2 := \{no\_cflct\} \end{array}$$

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#### Decide

SAT: 
$$\frac{I \in L \quad I, \overline{I} \notin M}{M := M|I}$$

$$\mathsf{CL}: \frac{I \in \mathcal{QA}(\Sigma) \qquad I \updownarrow \qquad I \Downarrow}{M := M | I \qquad \Sigma := \Sigma |}$$

$$\mathsf{CL} \text{ example: } \frac{\exists y P(a,y) \in \mathcal{QA}(\Sigma) \qquad M = Q(a)}{M = Q(a) | \ \exists y P(a,y)}$$

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#### Generalized resolution for conflict analysis

$$\frac{\mathcal{P} \Rightarrow \mathcal{Q} \cup \{\exists \vec{y} p(\vec{x}, \vec{y})\} \quad \{p(\vec{x}', \vec{y}')\} \cup \mathcal{P}' \Rightarrow \mathcal{Q}'}{(\mathcal{P} \cup \forall \vec{y}' \mathcal{P}' \Rightarrow \mathcal{Q} \cup \exists \vec{y}' \mathcal{Q}')\lambda}$$

# $\frac{\mathcal{P} \Rightarrow \mathcal{Q} \cup \{p(\vec{x}, \vec{y})\} \quad \{\forall \vec{x}' p(\vec{x}', \vec{y}')\} \cup \mathcal{P}' \Rightarrow \mathcal{Q}'}{(\forall \vec{x} \mathcal{P} \cup \mathcal{P}' \Rightarrow \exists \vec{x} \mathcal{Q} \cup \mathcal{Q}')\sigma}$

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**Basic properties** 

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- Sound
- Complete with additional rule for iterative deepening
- First order reasoning

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#### Example of system operation

- (Ax1)  $p(x, y) \land q(x, y) \Rightarrow \bot$ (Ax2)  $s(x) \Rightarrow \exists y \ q(x, y)$
- $(A\times 2) \quad s(x) \rightarrow \exists y \ q(x, y)$  $(A\times 3) \quad s(x) \lor q(y, y)$

(Conj)  $(\forall x \forall y \ p(x, y)) \Rightarrow \bot$ 

Rule applied	Σ	$\Gamma \setminus AX$ (lemmas)	Μ	$C_1 \Rightarrow C_2$
	а	Ø	p(x, y)	$\emptyset \Rightarrow \{no\_cflct\}$
Decide	a	Ø	p(x, y) s(x)	$\emptyset \Rightarrow \{ no\_cflct \}$
U.p.r. (Ax2)	a	Ø	$p(x, y) s(x), \exists y \ q(x, y)$	$\emptyset \Rightarrow \{no\_cflct\}$
Intro	a b	Ø	$p(x, y) s(x), \exists y \ q(x, y), q(a, b)$	$\emptyset \Rightarrow \{no\_cflct\}$
B.e. (Ax1)	ab	Ø	$p(x, y) s(x), \exists y \ q(x, y), q(a, b)$	$p(x, y) \land q(x, y) \Rightarrow \bot$
E.I. ∃ (Ax2)	a b	Ø	$p(x, y) s(x), \exists y \ q(x, y), q(a, b)$	$\forall y \ p(x, y) \land s(x) \Rightarrow \bot$
Learn	alb	$\forall y \ p(x, y) \land s(x) \Rightarrow \bot$	$p(x, y) \underline{s(x)}, \exists y \ q(x, y), q(a, b)$	$\forall y \ p(x, y) \land s(x) \Rightarrow \bot$
B.j.	а	$\forall y \ p(x, y) \land s(x) \Rightarrow \bot$	$p(x, y), \overline{s(x)}$	$\emptyset \Rightarrow \{ no\_cflct \}$
U.p.r. (Ax3)	а	$\forall y \ p(x, y) \land s(x) \Rightarrow \bot$	$p(x, y), \overline{s(x)}, q(y, y)$	$\emptyset \Rightarrow \{ no\_cflct \}$
B.e. (Ax1)	а	$\forall y \ p(x, y) \land s(x) \Rightarrow \bot$	$p(x, y), \overline{s(x)}, q(y, y)$	$p(x, y) \land q(x, y) \Rightarrow \bot$
E.r. (Ax3)	а	$\forall y \ p(x, y) \land s(x) \Rightarrow \bot$	$p(x, y), \overline{s(x)}, q(y, y)$	$p(x,x) \Rightarrow s(z)$
E.r. (lemma)	а	$\forall y \ p(x, y) \land s(x) \Rightarrow \bot$	$p(x, y), \overline{s(x)}, q(y, y)$	$p(x, x) \land \forall y \ p(z, y) \Rightarrow \bot$

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# Forward chaining proofs

$$\frac{s(x) \lor q(y, y) \quad p(x, y) \land q(x, y) \Rightarrow \bot}{p(x, x) \Rightarrow s(z)} \quad \frac{s(x) \Rightarrow \exists y \ q(x, y) \quad p(x, y) \land q(x, y) \Rightarrow \bot}{\forall y \ p(x, y) \land s(x) \Rightarrow \bot}$$

$$\frac{\frac{\perp}{q(a,b)} \Rightarrow (Ax1)}{\frac{\exists y \ q(a,y)}{q(y,y)} \Rightarrow (Ax1)} \xrightarrow{\frac{\exists y \ q(a,y)}{\exists y \ q(x,y)}} \frac{\exists}{\ln t} \Rightarrow (Ax2)}{\frac{\exists x \ q(x,y)}{s(x)} \lor (Ax3)}$$

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# Forward chaining proofs

 $\frac{s(x) \lor q(y, y) \quad p(x, y) \land q(x, y) \Rightarrow \bot}{p(x, x) \Rightarrow s(z)} \quad \frac{s(x) \Rightarrow \exists y \ q(x, y) \quad p(x, y) \land q(x, y) \Rightarrow \bot}{\forall y \ p(x, y) \land s(x) \Rightarrow \bot}$ 

 $\mathcal{AX}, \mathbf{p}(\mathbf{x}, \mathbf{y})$ 

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$$\frac{s(x) \lor q(y, y) \quad p(x, y) \land q(x, y) \Rightarrow \bot}{p(x, x) \Rightarrow s(z)} \qquad \frac{s(x) \Rightarrow \exists y \ q(x, y) \quad p(x, y) \land q(x, y) \Rightarrow \bot}{\forall y \ p(x, y) \land s(x) \Rightarrow \bot}$$

 $p(x, x) \land \forall y \ p(z, y) \Rightarrow \bot$ 

$$\frac{\overline{q(y,y)}}{\mathcal{AX}, p(x,y)} \quad \forall (Ax3)$$

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$$\frac{\overline{q(y,y)}}{\mathcal{AX}, p(x,y)} \quad \overline{s(x)} \quad \forall (Ax3)$$

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$$\frac{\frac{\perp}{q(y,y)} \Rightarrow (Ax1)}{\mathcal{AX}, p(x,y)} \xrightarrow{s(x)} \lor (Ax3)$$

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$$\frac{\frac{\perp}{q(y,y)} \Rightarrow (A \times 1)}{\mathcal{AX}, p(x,y)} \xrightarrow{s(x)} \lor (A \times 3)$$

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# Forward chaining proofs

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$$\frac{\perp}{q(y,y)} \Rightarrow (Ax1) \quad \overline{\frac{\exists y \ q(x,y)}{s(x)}} \Rightarrow (Ax2)$$
$$\frac{\forall AX, p(x,y)}{\forall (Ax3)} \quad \forall (Ax3)$$

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$$\frac{s(x) \lor q(y, y) \quad p(x, y) \land q(x, y) \Rightarrow \bot}{p(x, x) \Rightarrow s(z)} \xrightarrow{s(x) \Rightarrow \exists y \ q(x, y) \quad p(x, y) \land q(x, y) \Rightarrow \bot}{\forall y \ p(x, y) \land s(x) \Rightarrow \bot}$$

 $p(x, x) \land \forall y \ p(z, y) \Rightarrow \bot$ 

$$\frac{\frac{\bot}{q(y,y)} \Rightarrow (Ax1)}{\mathcal{AX}, p(x,y)} \xrightarrow{\frac{\exists y \ q(a,y)}{\exists y \ q(x,y)}} \underset{(Ax2)}{\text{isst}} \underset{(Ax2)}{\text{isst}}$$

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# Forward chaining proofs

$$\frac{s(x) \lor q(y, y) \quad p(x, y) \land q(x, y) \Rightarrow \bot}{p(x, x) \Rightarrow s(z)} \quad \frac{s(x) \Rightarrow \exists y \ q(x, y) \quad p(x, y) \land q(x, y) \Rightarrow \bot}{\forall y \ p(x, y) \land s(x) \Rightarrow \bot}$$

$$\frac{\frac{\bot}{\exists y \ q(a, y)} \Rightarrow (Ax1)}{\frac{\exists y \ q(a, y)}{\exists y \ q(x, y)}} \stackrel{\exists}{\exists y \ q(x, y)} \stackrel{\text{Inst}}{\Rightarrow (Ax2)} \\ \xrightarrow{a(y, y)} \downarrow (Ax3)$$

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 $p(x, x) \land \forall y \ p(z, y) \Rightarrow \bot$ 

$$\frac{\frac{\bot}{\exists y \ q(a, y)}}{\frac{q(y, y)}{q(y, y)}} \stackrel{\Rightarrow}{\Rightarrow} (Ax1) \xrightarrow{\frac{\exists y \ q(a, y)}{\exists y \ q(x, y)}} \stackrel{\exists}{\Rightarrow} (Ax2) \xrightarrow{Inst}{\Rightarrow} (Ax2)$$

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# Forward chaining proofs

$$\frac{s(x) \lor q(y, y) \quad p(x, y) \land q(x, y) \Rightarrow \bot}{p(x, x) \Rightarrow s(z)} \quad \frac{s(x) \Rightarrow \exists y \ q(x, y) \quad p(x, y) \land q(x, y) \Rightarrow \bot}{\forall y \ p(x, y) \land s(x) \Rightarrow \bot}$$

$$\frac{\frac{\perp}{q(a,b)} \Rightarrow (Ax1)}{\frac{\exists y \ q(a,y)}{q(y,y)} \Rightarrow (Ax1)} \xrightarrow{\frac{\exists y \ q(a,y)}{\exists y \ q(x,y)}} \frac{\exists}{\ln t} \Rightarrow (Ax2)}{\frac{\exists x \ q(x,y)}{s(x)} \lor (Ax3)}$$

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Abstract State Transition Systems for SAT Abstract State Transition Systems for CL

# Readable proof

- Assume  $\forall x \forall y \ p(x, y)$ .
- By (Ax3), it holds  $\forall x \ s(x)$  or  $\forall y \ q(y, y)$ .
- Assume  $\forall y \ q(y, y)$ .
  - By (Ax1), this leads to contradiction.
- Assume  $\forall x \ s(x)$ .
  - By (Ax2), it holds  $\forall x \exists y \ q(x, y)$ .
  - From  $\forall x \exists y \ q(x, y)$ , it holds  $\exists y \ q(a, y)$ .
  - From  $\exists y \ q(a, y)$ , there is b such that q(a, b).
  - By (Ax1), this leads to contradiction.

# Related work

	FOL fragment	Lemma learning	Reasoning	Readable proofs
Euclid	CL	No	Ground	Yes
(Janičić, Kordić)				
Bezem's CL prover	CL	No	Ground	Yes
(Bezem)				
Geo	CL-like	Yes	Ground	No
(de Nivelle)				
ArgoCLP	CL	No	Ground	Yes
(Stojanović, Pavlović, Janičić)				
Darwin	Clausal	Yes	FO	No
(Baumgartner, Tinelli, Fuchs, Pelzer)				
EPR	Clausal w.o.	Yes	FO	No
(Piskač, de Moura, Bjørner)	functions			

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Conclusions and future work

- Hopefully, efficient CDCL-based CL prover
- Applications in geometry (and education)

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